



PIC24F Flash Program Memory

HIGHLIGHTS

This section of the manual contains the following major topics:

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Note: This family reference manual section is meant to serve as a complement to device data sheets. Depending on the device variant, this manual section may not apply to all PIC24F devices.

Please consult the note at the beginning of the “Flash Program Memory” chapter in the current device data sheet to check whether this document supports the device you are using.

Device data sheets and family reference manual sections are available for download from the Microchip Worldwide Web site at: <http://www.microchip.com>

1.0 INTRODUCTION

All PIC24F devices have an internal programmable Flash array for the execution of user code. The high-endurance Flash array provides great flexibility in code development and storage, combining a long retention life with a high number of read/write cycles.

2.0 PROGRAM MEMORY ARCHITECTURE

PIC24F devices address a 4M x 24-bit program memory address space, as shown in [Figure 2-1](#). The program memory map is equally divided into the user memory space (000000h to 7FFFFFFh) and the configuration (or test) memory space (800000h to FFFFFFFh).

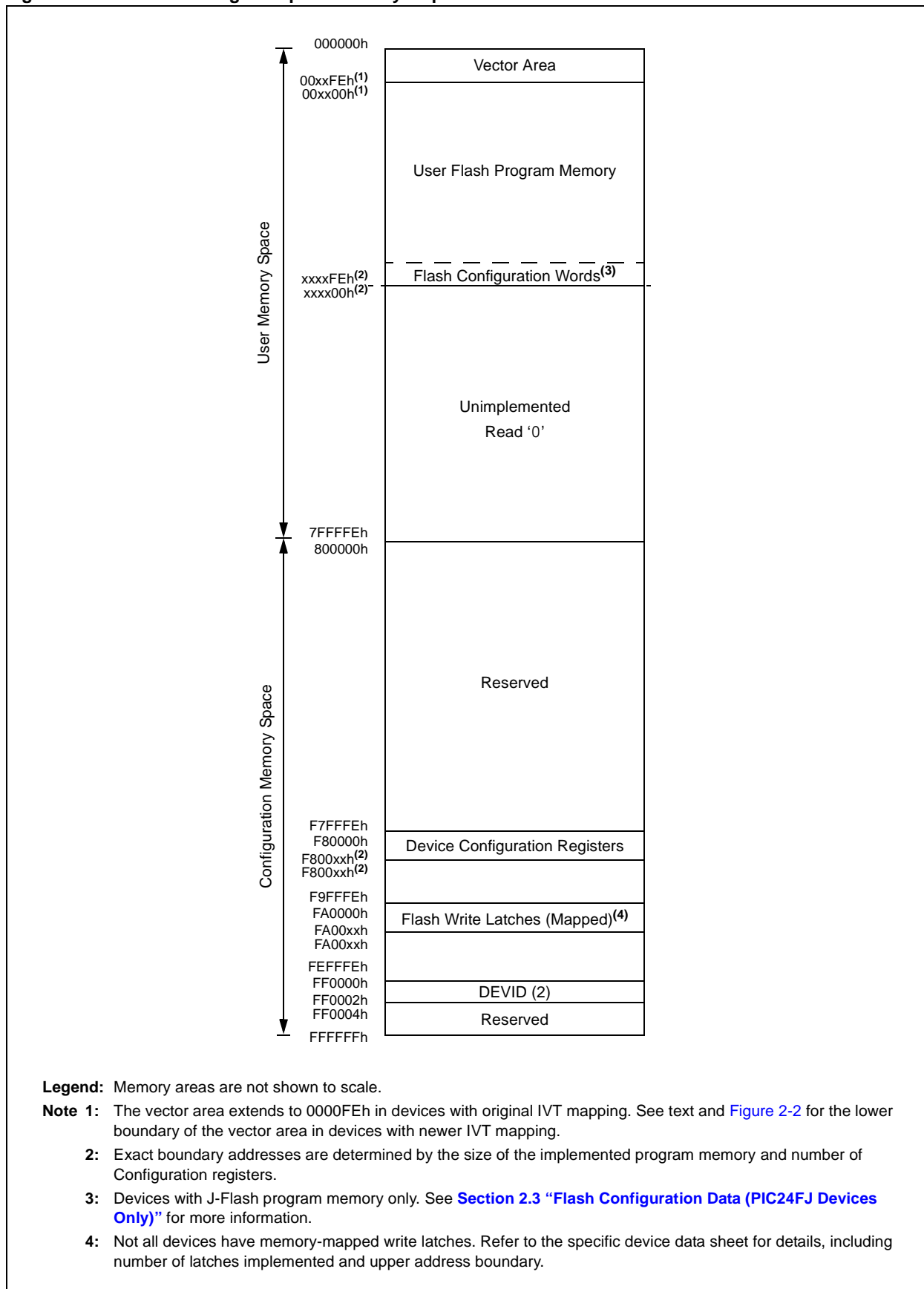
The user program space contains the Reset vector, Interrupt Vector Tables (IVTs) and program memory. There are three methods for accessing program space:

1. The 23-bit Program Counter (PC).
2. Table Read (TBLRD) and Table Write (TBLWT) instructions.
3. By mapping any 32-Kbyte segment of program memory into the data memory address space.

Implemented program memory can be further divided into the vector area, which includes the Reset and interrupt vectors, and the code area, which also includes the Flash configuration data. Accessing unimplemented areas of the user program space (i.e., above the upper implemented boundary of program memory) will cause an illegal address trap.

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Figure 2-1: Default Program Space Memory Map for PIC24F Devices



Legend: Memory areas are not shown to scale.

- Note 1:** The vector area extends to 0000FEh in devices with original IVT mapping. See text and [Figure 2-2](#) for the lower boundary of the vector area in devices with newer IVT mapping.
- 2:** Exact boundary addresses are determined by the size of the implemented program memory and number of Configuration registers.
- 3:** Devices with J-Flash program memory only. See [Section 2.3 “Flash Configuration Data \(PIC24FJ Devices Only\)”](#) for more information.
- 4:** Not all devices have memory-mapped write latches. Refer to the specific device data sheet for details, including number of latches implemented and upper address boundary.

2.1 Vector Area

The vector area starts at the beginning of program memory space, at 000000h. It contains the master Reset vector, the hardware trap vectors and the Interrupt Vector Tables (IVTs) for all implemented hardware interrupts. Hardware trap vectors immediately follow the Master Reset address. The hardware interrupt vectors immediately follow the trap vectors, always starting with Interrupt Vector 0.

The exact implementation of the vector area falls into one of two categories. Most PIC24F devices use the original, fixed IVT mapping. Some newer PIC24F devices, particularly those that implement CodeGuard™ security, use a different mapping. Refer to the device-specific data sheet to determine which version is implemented. [Figure 2-2](#) shows the structure of the different mappings.

2.1.1 ORIGINAL IVT MAPPING

In the original PIC24F families and many subsequent PIC24F device families, the vector area is a fixed region that extends to 0001FEh. The IVTs provide space for 8 hard trap vectors and 118 interrupt vectors.

For the main IVT, trap vectors extend from 000006h to 000012h. Interrupt vectors extend from Vector 0 at 0000014h, to Vector 117 at 0000FEh.

The Alternate IVT (AIVT) duplicates the structure of the IVT and can be used to store addresses for alternate exception handling. The AIVT directly follows the IVT, with trap vectors from 000106h to 000112h and interrupt vectors from 000114h to 0001FEh.

Both IVT and AIVT are implemented and available on all devices.

2.1.2 NEWER IVT MAPPING

Newer PIC24F devices implement essentially the same IVTs as in the original mapping (although some of the hard trap vectors may reside at different addresses within the same address range). Unlike devices with original IVT mapping, the AIVT is not permanently allocated in program memory at a fixed address range. It is only present when:

- CodeGuard security is configured for a Boot Segment (BS) with a size of at least two pages (set by the FBSLIMx Configuration bits), and
- AIVT is enabled by programming the AIVTDIS Configuration bit to '0'.

When AIVT is disabled, the vector area's upper boundary is 0000FEh (i.e., at the end of the main IVT). When the AIVT is enabled, it is located at an address range starting at the beginning of the last page of the Boot Segment; each vector is located at a fixed offset from the page boundary.

Depending on the size of the Boot Segment selected, the AIVT may not be contiguous with the main IVT. However, the total size and content (i.e., vector order) of the AIVT mirrors those of the IVT.

2.1.3 VECTOR AREA SECURITY

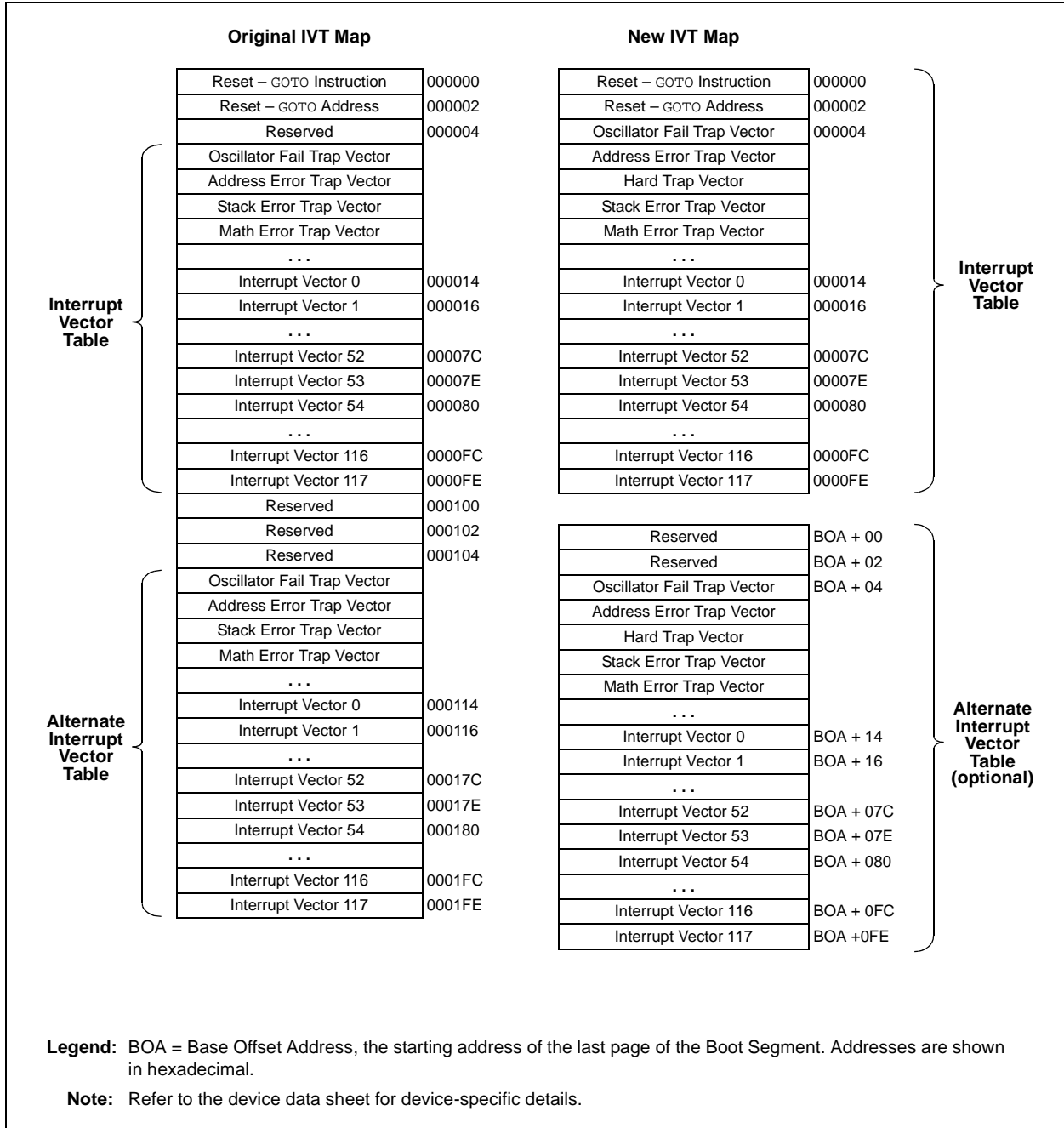
Devices with the original IVT mapping generally use a limited implementation of code security. Many devices only provide security for the General Segment (GS), which includes both the Code Segment (CS) and the Vector Segment (VS). Other devices provide for Boot Segment (BS) security, which does not include the vector area. Refer to the device data sheet for specific implementation details.

Devices with the newer IVT mapping also implement CodeGuard security. In these devices, the vector area roughly corresponds to the Vector Segment (VS). Depending on the security configuration, the vector area may be treated as part of the Boot Segment (BS) or the General Segment (GS). Security settings for the vector area are not determined independently, but by which segment (BS or GS) the vector area is in.

In addition, the implementation of the AIVT within the BS means that it will always be a part of a higher security Code Segment. This makes the AIVT useful for handling interrupts from high-security code applications, as well as bootloaders.

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Figure 2-2: Vector Area Detail



2.2 Code Area

The code area is the area of user program memory that contains the user's application code. It extends from the end of the vector area to the end of the implemented memory.

If a Boot Segment (BS) is implemented, it starts at the end of the vector area and extends for a predetermined range. In devices that implement code security, the part of the code area that is not defined as a Boot Segment corresponds to the General Segment (GS).

With the exception of PIC24F J-Flash devices, as described in the following section, the entire area is available for application code.

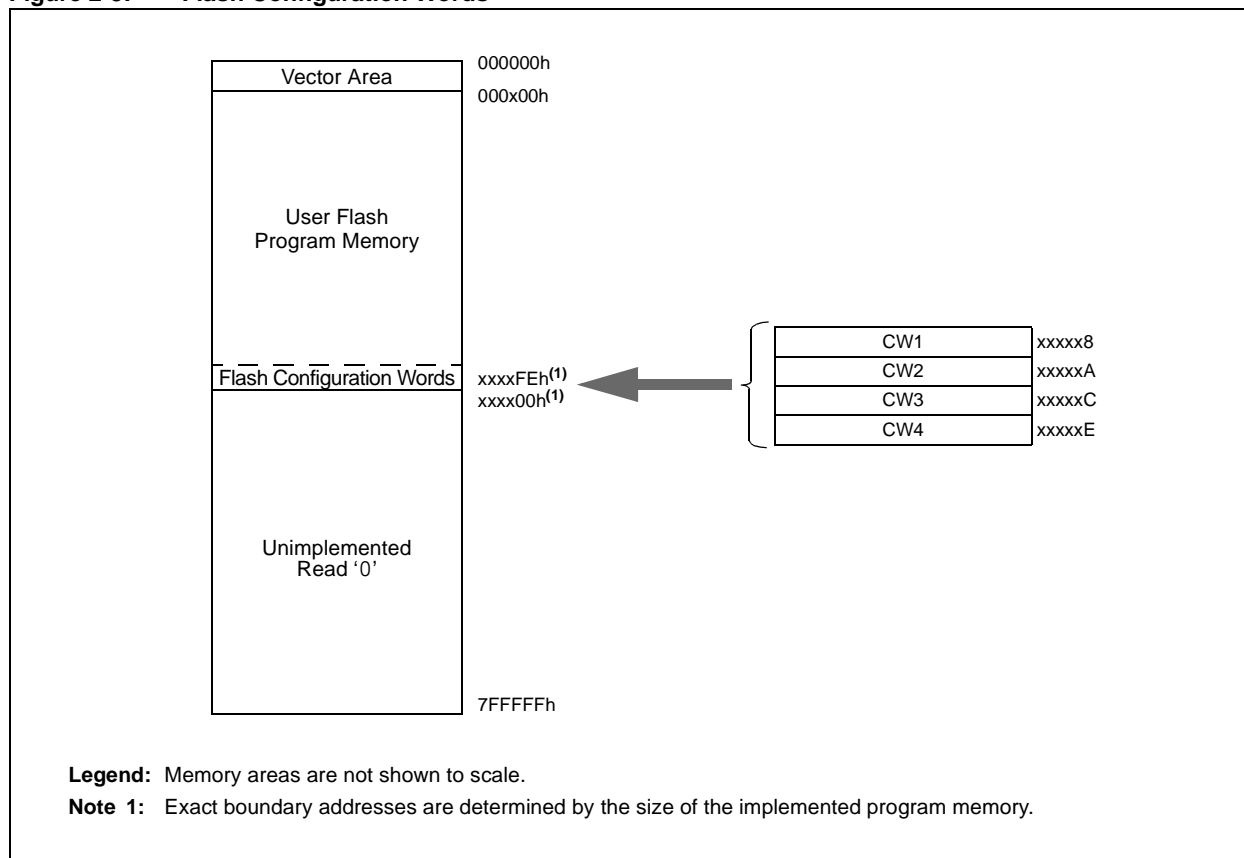
2.3 Flash Configuration Data (PIC24FJ Devices Only)

All PIC24F devices with J-Flash program memory reserve the area at the end of the implemented program memory range (typically, the last row) for device configuration data. These memory locations are referred to as Flash Configuration Words. On device Reset, the configuration information stored in this area is written into the appropriate device Configuration registers, which are located starting at F80000h in the configuration memory space. In most cases, device configuration data can only be programmed by programming the desired values to the Flash Configuration Words.

The number, order and organization of the Flash Configuration Words varies between device families. Figure 2-3 shows a typical example for Flash Configuration Words with four implemented words. Refer to the device data sheet for family-specific information.

Note: PIC24F devices with K-Flash memory do not use Flash Configuration Words. The device Configuration bits are programmed directly at their locations in configuration memory space (starting at F80000h), using special Table Write instructions or programming operations. Refer to the specific device data sheet for more details.

Figure 2-3: Flash Configuration Words



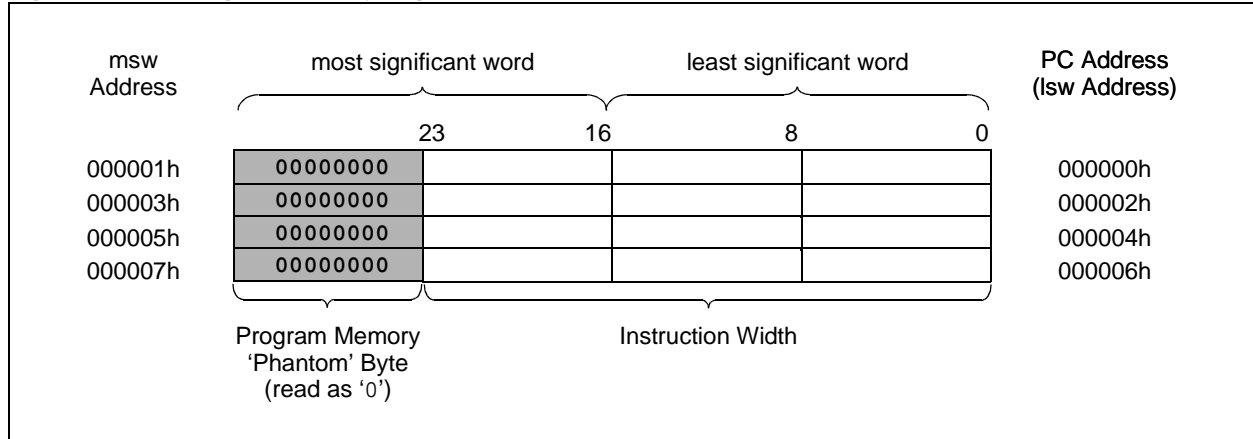
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2.4 Memory Organization

The program memory space is organized as word-addressable blocks. Although it is treated as 24 bits wide, it is more appropriate to think of each address of the program memory as a lower and upper word, with the upper byte of the upper word being unimplemented. The lower word always has an even address, while the upper word has an odd address (Figure 2-4).

Program memory addresses and the PC are always word-aligned on the lower word (i.e., the LSB is always '0'). Addresses are incremented or decremented by two during code execution.

Figure 2-4: Program Memory Organization



2.4.1 ADDRESSING PROGRAM MEMORY

For normal code execution, the Effective Address (EA) for execution is provided by the Program Counter (PC). The PC is 23 bits wide, allowing direct access to any location in the user program space. PC<0> is fixed as '0' in order to maintain program instruction alignment. The PC is incremented to the next sequential address by incrementing PC<1>, thus increasing the value of the PC by two.

For Table Read and Table Write operations, the EA is created by concatenating the 16-bit address from one of the W registers with the 8-bit address from the TBLPAG register. This permits table operations access to both the user and configuration spaces. Address generation for table operations is discussed in more detail in [Section 3.1 "Address Generation for Table Operations"](#).

For Extended Data Space (EDS) and Program Space Visibility (PSV) operations, the EA is created by concatenating the lower 15 bits of a W register with the 8-bit address from either the PSVPAG, DSRPAG or DSWPAG registers. Extended Data Space and Program Space Visibility operations are discussed in the *dsPIC33/PIC24 Family Reference Manual*, "[Data Memory with Extended Data Space \(EDS\)](#)" (DS39733).

3.0 TABLE OPERATION INSTRUCTIONS

The table instructions provide one method of transferring data between the program memory space and the data memory space of the PIC24F devices. A summary of the table instructions used during programming of the Flash program memory is provided in this section. There are four basic table instructions:

- TBLRDL: Table Read Low
- TBLRDH: Table Read High
- TBLWTL: Table Write Low
- TBLWTH: Table Write High

The TBLRDL and the TBLWTL instructions are used to read and write to bits<15:0> of program memory space. TBLRDL and TBLWTL can access program memory in Word or Byte mode.

The TBLRDH and TBLWTH instructions are used to read or write to bits<23:16> of program memory space. TBLRDH and TBLWTH can access program memory in Word or Byte mode. Since the program memory is only 24 bits wide, the TBLRDH and TBLWTH instructions have the ability to address an upper byte of program memory that does not exist. This byte is called the 'phantom byte'. Any read of the phantom byte returns 00h; a write to the phantom byte has no effect.

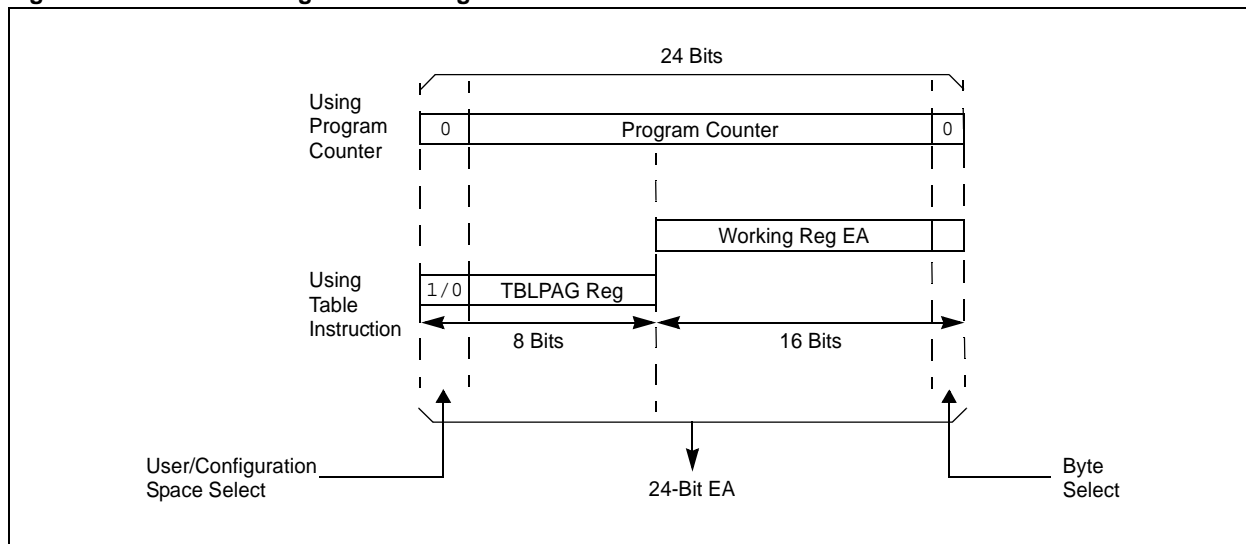
When any of the table instructions are used in Byte mode, the LSb of the table address will be used as the byte select bit. The LSb determines which byte in the high or low program memory space is accessed.

3.1 Address Generation for Table Operations

Figure 3-1 illustrates how the program memory is addressed using the table instructions. A 24-bit program memory address is formed using the TBLPAG<7:0> bits and the Effective Address (EA) from a W register, specified in the table instruction (the 24-bit Program Counter is shown for reference). The upper 23 bits of the EA are used to select the program memory location. For the Byte mode table instructions, the LSb of the W register EA is used to pick which byte of the 16-bit program memory word is addressed; '1' selects bits<15:8>, '0' selects bits<7:0>. The LSb of the W register EA is ignored for a table instruction in Word mode.

In addition to the program memory address, the table instructions also specify a W register (or a W Pointer to a memory location) that is the source of the program memory data to be written or the destination for a program memory read. For a Table Write operation in Byte mode, bits<15:8> of the source Working register are ignored.

Figure 3-1: Addressing for Table Registers

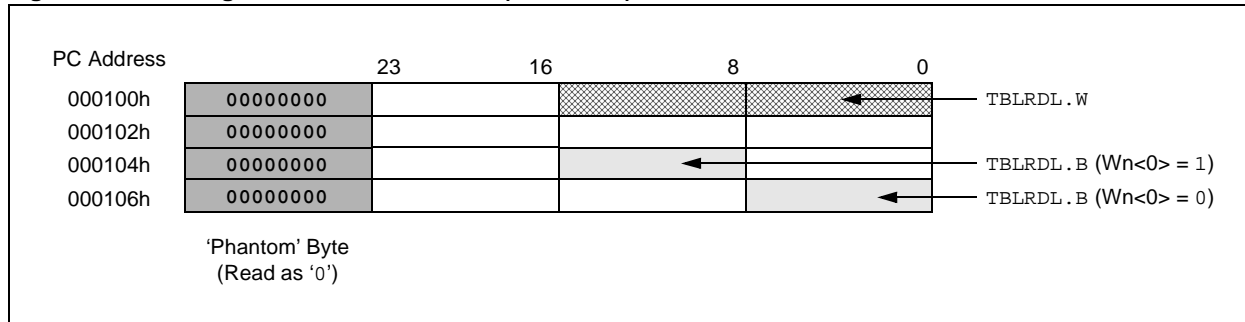


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3.2 Low Word Access

The `TBLRDL` and `TBLWTL` instructions are used to access the lower 16 bits of program memory data. The LSB of the W register address is ignored for word-wide table accesses. For byte-wide accesses, the LSB of the W register address determines which byte is read. Figure 3-2 illustrates the program memory data regions accessed by the `TBLRDL` and `TBLWTL` instructions.

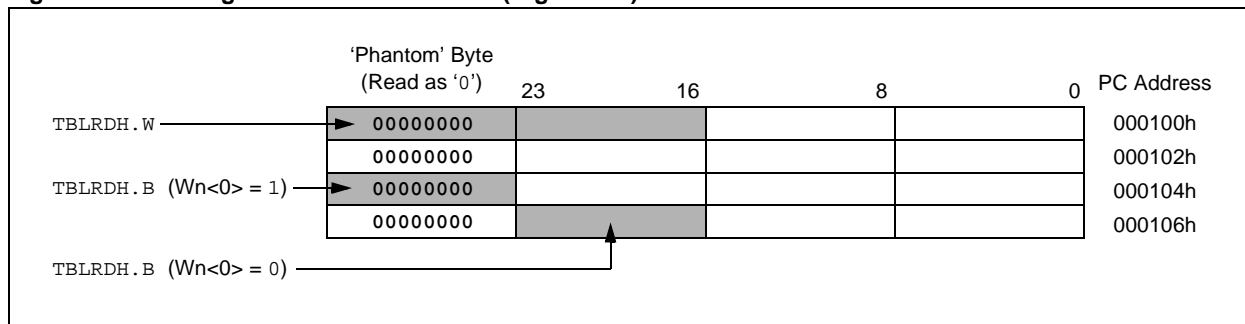
Figure 3-2: Program Data Table Access (Low Word)



3.3 High Word Access

The `TBLRDH` and `TBLWTH` instructions are used to access the upper 8 bits of the program memory data. These instructions also support Word or Byte Access modes for orthogonality, but the high byte of the program memory data will always return '0', as shown in Figure 3-3.

Figure 3-3: Program Data Table Access (High Word)



3.4 Table Writes and Write Latches

Table Write instructions do not write directly to the nonvolatile program memory. Instead, the instructions load holding latches that store the write data. When all of the holding latches have been loaded, the actual memory programming operation is started by executing a special sequence of instructions.

The number of write latches implemented determines the type of programming options that are available (e.g., word, double-word or row) and is device-specific. Refer to the specific device data sheet for more information.

Holding latches may be implemented in one of two ways: unmapped and memory-mapped. For unmapped devices, the latches are built into the Flash controller and are not directly addressable; they can only be accessed using Table Write instructions. The target address for programming is specified in the programming sequence.

For memory-mapped devices, programming data is written to one or more latches, mapped to a region in configuration space, starting at FA0000h. The target address for programming is specified by a special address register.

Specific algorithms for Table Write operations in both unmapped and memory-mapped devices are covered in subsequent sections.

3.5 Data Storage in Program Memory

It is assumed that for most applications, the high byte (P<23:16>) will not be used for data, making the program memory appear 16 bits wide for data storage. It is recommended that the upper byte of program data be programmed either as a NOP (00h or FFh), or as an illegal opcode (3Fh) value, to protect the device from accidental execution of stored data. The TBLRDH and TBLWTH instructions are primarily provided for array program/verification purposes and for those applications that require compressed data storage.

3.6 Program Memory Bit Behavior

Bits in Flash program memory can only be programmed from '1' to '0' and can be subsequently erased to '1'. Using a programming sequence to set a bit to a '1' will have no effect.

3.7 Using Table Read Instructions

Table Reads require two steps. First, an Address Pointer is set up using the TBLPAG register and one of the W registers. Then, the program memory contents at the address location may be read.

The code examples in [Example 3-1](#) and [Example 3-2](#) demonstrate how to read a word of program memory using the table instructions. These examples use the `tblpage()` and `tbloffset()` directives, which are provided by the Microchip assembler for PIC24F devices. These directives select the appropriate TBLPAG and W register values for the table instruction from a program memory address value. Refer to the "MPLAB[®] Assembler, Linker and Utilities for PIC24 MCUs and dsPIC[®] DSCs User's Guide" (DS51317) for more information.

Example 3-1: Byte Read (in Assembly)

```
                                ; Read program memory address 0x012340
                                ; Create 24 bit EA for read by loading TBLPAG and W1
MOV    #0x0001, W0              ; Load TBLPAG register with read address <23:16>
MOV    W0, TBLPAG
MOV    #0x2340, W1              ; Load W1 with read address <15:0>
                                ; Read data from program memory into W registers
TBLRDL.B [W1++], W2            ; W2 contains low byte
TBLRDL.B [W1--], W3            ; W3 contains middle byte
TBLRDH.B [W1], W4              ; W4 contains high byte
```

Example 3-2: Word Read of Variable from Program Memory (in Assembly)

```
PROG_DATA: .word 0x1234         ; 16 bit variable in program memory
                                ; Create EA for read by loading TBLPAG and W0
MOV    #tblpage(PROG_DATA), W0 ; Get upper byte address of variable PRG_DATA
MOV    W0, TBLPAG              ; Load upper address into TBLPAG register
MOV    #tbloffset(PROG_DATA), W1 ; Load W1 with lower address word
                                ; of variable PRG_DATA
                                ; Read data from program memory
                                ; into W registers
TBLRDL [W1], W2                ; W2 contains 16 bit variable data
```

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The code examples in [Example 3-3](#) and [Example 3-4](#) demonstrate how to read a word of program memory in C. These examples use the MPLAB XC16 C compiler's `__builtin_tblpage()` and `__builtin_tbloffset()` functions to return the values of TBLPAG and the offset, and `__builtin_tblrldl` and `__builtin_tblrldh` instructions to access the Table Read assembler instructions. Refer to the “MPLAB® XC16 C Compiler User's Guide” (DS50002071) for more information.

Example 3-3: Word Read (in C)

```
int addrOffset, readDataL, readDataH;
// Read 24 bits of data memory from address 0x012340
// Create 24 bit EA for read by loading TBLPAG
TBLPAG = 0x0001; // Load TBLPAG register with read address <23:16>
addrOffset = 0x2340; // Load offset with read address <15:0>
// Read data from program memory
readDataL = __builtin_tblrldl(addrOffset); // readDataL contains lower word data
readDataH = __builtin_tblrldh(addrOffset); // readDataH contains high byte data
```

Example 3-4: Read of Variable from Program Memory (in C)

```
int addrOffset, readDataL;
// Create variable in program space at address 0x012340
__prog_int_attribute__ ((space(prog), address(0x012340))) PROG_ADDR = 0xABCD;
// Create 24 bit EA for read by loading TBLPAG
TBLPAG = __builtin_tblpage(&PROG_ADDR); // Load upper address into TBLPAG register
addrOffset = __builtin_tbloffset(&PROG_ADDR); // Mask for word alignment
// Read data from program memory
readDataL = __builtin_tblrldl(addrOffset); // readDataL contains 16 bit variable data
```

3.8 Using Table Write Instructions

Table Write operations differ between devices with unmapped and memory-mapped write latches in the way that the destination address for programming is specified. In unmapped devices, the programming target is specified by the TBLPAG and Wn registers. In memory-mapped devices, the NVMADR/NVMADRU registers specify the target address; TBLPAG and Wn specify the address of the write latches.

3.8.1 TABLE WRITES WITH UNMAPPED WRITE LATCHES

For unmapped devices, Table Write operations are done in three steps:

1. Load TBLPAG and a Wn register with the 24-bit destination address.
2. Load the Wn register with data or a pointer to write data.
3. Perform the TBLWT instructions to load the write latches.

For word programming, this sequence only needs to be done once, as shown in [Example 3-5](#).

Example 3-5: Loading Write Latches, Word Programming (in Assembly)

```
; Set up a pointer to the location to be written (x012340 for this example)
MOV    #0x0001, W0
MOV    W0, TBLPAG           ; Load TBLPAG with upper address
MOV    #0x2340, W1         ; Load W1 with lower address word
; Load write data into Wn registers
MOV    #WRITE_DATA_1L, W2
MOV    #WRITE_DATA_1H, W3
; Perform the TBLWT instructions to load the write latches
TBLWTL W2, [W1]
TBLWTH W3, [W1]
```

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For devices that support row programming, the sequence is repeated in a loop until all write latches are written. [Example 3-6](#) loads 64 write latches and uses W1 as a pointer to the write data. W1 is post-incremented to point to the next byte to be written to the write latch.

Example 3-6: Loading Write Latches, Row Programming (in Assembly)

```
; Set up a pointer to the location to be written (x010200 for this example)
MOV    #0x0001, W0
MOV    W0, TBLPAG           ; Load TBLPAG with upper address
MOV    #0x0200, W1         ; Load W1 with lower address word
; Set up write data address pointer, W2 point to data in RAM
MOV    #WRITE_ADDR, W2
; Perform the TBLWT instructions to load the write latches
MOV    #64, W3             ; Set loop count to number of write latches
loop:
TBLWTL.b [W2++], [W1++]   ; Load lower byte to write latch
TBLWTL.b [W2++], [W1--]   ; Load middle byte to write latch
TBLWTH.b [W2++], [W1]     ; Load high byte to write latch
INC2   W1, W1              ; Increment to next write latch
DEC    W3, W3              ; Decrement loop count
BRA    NZ, loop
```

3.8.2 TABLE WRITES WITH MEMORY-MAPPED LATCHES

Table Write operations are done in three steps:

1. Load TBLPAG and a Wn register with the 24-bit address of the write latch.
2. Load the Wn register with data or a pointer to write data.
3. Perform the TBLWT instructions to load the write latches.

The sequence for double-word programming in [Example 3-7](#) performs Step 3 (TBLWT sequence) twice to write the second word. For devices that support row programming, the sequence is repeated in a loop until all write latches are written. [Example 3-8](#) loads 64 write latches and uses W1 as a pointer to the write data. W1 is post-incremented to point to the next write latch.

Example 3-7: Loading Write Latches, Double-Word Programming (in Assembly)

```
; Set up the address pointer to 1st write latch
MOV    0xFA, W0
MOV    W0, TBLPAG           ; Load TBLPAG with write latch upper address
MOV    0x0, W0              ; Load W0 with lower write latch address
; Load write data into Wn registers
MOV    #PROG_LOW_WORD_1, W2
MOV    #PROG_HI_BYTE_1, W3
MOV    #PROG_LOW_WORD_2, W4
MOV    #PROG_HI_BYTE_2, W5
; Perform the table writes to load the latch
TBLWTL W2, [W0]
TBLWTH W3, [W0++]
TBLWTL W4, [W0]
TBLWTH W5, [W0++]
```

Example 3-8: Loading Write Latches, Row Programming (in Assembly)

```
; Set up a pointer to write latch
MOV    #0x00FA, W0
MOV    W0, TBLPAG           ; Load TBLPAG with upper write latch address
MOV    #0x0000, W1         ; Load W1 with lower address word
; Set up write data address pointer, W2 point to data in RAM
MOV    #WRITE_ADDR, W2
; Perform the TBLWT instructions to load the write latches
MOV    #64, W3             ; Set loop count to number of write latches
loop:
TBLWTL.b [W2++], [W1++]   ; Load lower byte to write latch
TBLWTL.b [W2++], [W1--]   ; Load middle byte to write latch
TBLWTH.b [W2++], [W1]     ; Load high byte to write latch
INC2   W1, W1              ; Increment to next write latch
DEC    W3, W3              ; Decrement loop count
BRA    NZ, loop
```

4.0 FLASH MEMORY PROGRAMMING

PIC24F devices can be programmed by any one of three methods:

- Run-Time Self-Programming (RTSP)
- In-Circuit Serial Programming™ (ICSP™)
- Enhanced In-Circuit Serial Programming (EICSP)

RTSP is performed by the application software during execution, while ICSP and EICSP are performed from an external programmer using a serial data connection to the device. ICSP and EICSP allow much faster programming time than RTSP.

RTSP techniques are described in this section. The ICSP and EICSP protocols are defined in the Programming Specification documents for the respective devices, which can be downloaded from the Microchip web site (www.microchip.com).

4.1 Registers

All programming operations are controlled through two registers: NVMCON and NVMKEY.

4.1.1 NVMCON REGISTER

The NVMCON register ([Register 4-1](#)) controls all Flash programming operations. The NVMOP<5:0> bits field selects the particular write or erase operation to be performed, while the ERASE bit (NVMCOM<6>) determines if the operation is an erase or program operation.

The WR bit (NVMCOM<15>) triggers the appropriate operation; it remains set until the operation has been completed and is then cleared by hardware. The WREN bit (NVMCOM<14>) enables or disables write and erase operations; WR cannot be set to trigger operations when WREN is clear.

4.1.2 NVMKEY REGISTER

NVMKEY is a write-only register that is used to prevent accidental writes or erasures of Flash memory; only the lower byte is implemented. To start a program or erase sequence, an “unlock” sequence of two writes is performed on the register:

1. Write 55h to NVMKEY<7:0>.
2. Write AAh to NVMKEY<7:0>.

After this sequence, a write will be allowed to the NVMCON register for one instruction cycle. The critical timing of the instruction sequence requires that applications written in C use in-line assembler directives to directly execute the sequence. Alternatively, the MPLAB XC16 C Compiler includes the built-in function, `__builtin_write_NVM`, to correctly execute the sequence, including the setting of the WR bit. For more information, refer to the “MPLAB® XC16 C Compiler User’s Guide” (DS50002071).

When initiating a programming or erase operation, it is recommended to first disable all device interrupts for at least five instruction cycles; this prevents an unexpected hardware event from interrupting the unlock sequence or setting the WR bit. In assembler, this is accomplished with the instruction, `disi #5`. In MPLAB XC16 C Compiler, the built-in function, `__builtin_disi(5)`, serves the same purpose.

4.1.3 NVMADR AND NVMADRU

For devices with memory-mapped write latches, the NVMADR and NVMADRU registers are implemented to contain the destination address of a Flash memory write. NVMADR is implemented as a 16-bit register and contains the lower 16 bits of the 24-bit address. NVMADRU is also 16 bits, but only implements the lower byte; it contains the upper 8 bits of the address.

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Register 4-1: NVMCON: NVM Flash Programming Control Register

R/S-0 ⁽¹⁾	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	U-0
WR	WREN	WRERR	PGMONLY ⁽²⁾	—	—	—	—
bit 15							bit 8

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	ERASE	NVMOP5 ⁽²⁾	NVMOP4 ⁽²⁾	NVMOP3	NVMOP2	NVMOP1	NVMOP0
bit 7							bit 0

Legend:	S = Settable Only bit
R = Readable bit	W = Writable bit
-n = Value at POR	'1' = Bit is set
	U = Unimplemented bit, read as '0'
	'0' = Bit is cleared
	x = Bit is unknown

- bit 15 **WR:** Write Control bit⁽¹⁾
 1 = Initiates a Flash program/erase operation; cleared by hardware upon completion of operation
 0 = Program/erase operation is complete and inactive
- bit 14 **WREN:** Program/Erase Enable bit
 1 = Allows program/erase cycles
 0 = Inhibits programming/erasing of memory or fuse elements
- bit 13 **WRERR:** Sequence Error Flag bit
 1 = An improper program/erase termination has occurred or an unimplemented programming operation has been selected
 0 = A program or erase operation is under way, has completed normally or has yet to start
- bit 12 **PGMONLY:** NVM Power-Down in Idle Enable bit⁽²⁾
 Not used in Flash program memory operations; available only in devices with data EEPROM.
- bit 11-7 **Unimplemented:** Read as '0'
- bit 6 **ERASE:** Erase/Program Enable bit
 1 = Performs the erase operation specified by the NVMOPx bits field on the next WR command
 0 = Performs the program operation specified by the NVMOPx bits field on the next WR command
- bit 5-0 **NVMOP<5:0>:** NVM Operation Select bits (initiated by the next setting of WR)⁽²⁾
 Valid program/erase operations are device-specific. Refer to the specific device data sheet.

- Note 1:** This bit is also reset on a BOR.
- Note 2:** The PGMONLY and NVMOP<5:4> bits are not implemented for all versions of Flash memory. Refer to the specific device data sheet for more information.

4.2 Run-Time Self-Programming (RTSP)

RTSP allows the user code to modify Flash program memory contents. RTSP is accomplished using `TBLRD` (Table Read) and `TBLWT` (Table Write) instructions, and the NVM Control registers. PIC24F devices support the following Flash programming operations:

- Flash Page Erases
- Row Programming (either latch-based or RAM-based)
- Word Programming
- Double-Word Programming (select devices only)

Flash programming via RTSP is performed either with blocks of memory called rows, or with one or two words of Flash memory. Prior to programming, a memory location must be erased. Erase operations are performed on blocks of memory called pages, which consist of multiple rows. The size of a row will vary by device; refer to the device data sheet for details. Typically, for PIC24F devices, a page is defined as eight (8) rows. This document uses examples with 64 instructions per row (512 instructions per page).

4.2.1 FLASH PROGRAMMING ALGORITHM AND EXAMPLES

Flash programming operations are controlled using the `NVMCON` and `NVMKEY` registers. A complete programming sequence is necessary for programming or erasing the internal Flash in RTSP mode. Setting the `WR` bit (`NVMCON<15>`) starts the operation and the `WR` bit is automatically cleared when the operation is finished.

An erase operation must be performed before Flash writes. Since the smallest erase operation size is one page, it is necessary for word and row programming operations to temporarily move the remainder of the page data to RAM, and then write it back to memory. Table Read instructions can be used to fill a data buffer that can then be written back to memory.

Note: On PIC24F devices with J-Flash program memory, erasing the last page of program memory also erases the Flash Configuration Words. If the device also implements security features, such as write protection, erasing the Configuration Words may enable security and prevent further programming changes. Refer to the specific device data sheet and programming specification for more information on code security features.

The CPU stalls until the programming operation is finished. The CPU will not execute any instructions or respond to interrupts during this time. Interrupts that occur during the programming cycle will remain pending until the cycle completes.

If a POR or BOR event occurs while an RTSP erase or programming operation is in progress, the RTSP operation is aborted immediately. The user should execute the RTSP operation again after the device comes out of Reset. If an `EXTR`, `SWR`, `WDTO`, `TRAPR`, `CM` or `IOPUWR` Reset event occurs while an RTSP erase or programming operation is in progress, the device will be reset only after the RTSP operation is complete. Two `NOB` instructions should always follow erase and program operations.

Programming a page of Flash program memory with RTSP involves three steps:

1. Create a RAM image of the page data to be modified.
2. Erase the page.
3. Program the page.

It is also recommended to verify the data written to memory against the RAM image to ensure integrity.

4.2.2 CREATE A RAM IMAGE

The RAM image must be read starting from a page address boundary. Perform these two steps to create a RAM image of the data page to be modified:

1. Read the content of the Flash program memory page using Table Read instructions and store it into data RAM as a data image.
2. Modify the RAM image as required.

4.2.3 ERASE THE PAGE

Page erase operations erase one page (8 rows) of program memory. A page erase should always be done before any programming operation is started. TBLPAG and one of the W registers are loaded with the starting address of the page to be erased, and a dummy TBLWT is executed to load this address into the Flash controller. The program memory must be erased at an even page address boundary. See the “**Flash Program Memory**” chapter of the specific device data sheet to determine the size of the Flash page.

To perform a page erase:

1. Set the NVMOPx bits field for a word program operation (refer to the device data sheet for the proper value).
2. Set the ERASE bit (NVMCON<6>).
3. For devices with non memory-mapped write latches, write the starting address of the page to be erased into TBLPAG and a W register, and execute a dummy TBLWT command, as shown in [Example 4-1](#). For devices with memory-mapped write latches, write the starting address of the page to be erased into NVMADR/NVMADRU, as shown in [Example 4-2](#).
4. Disable interrupts.
5. Write the key sequence to the NVMKEY register (see [Section 4.1.2 “NVMKEY Register”](#)).
6. Set the WR bit (NVMCON<15>) to start the erase cycle.
7. Execute two NOP instructions. The WR bit is cleared when the erase cycle is complete.

Example 4-1: Page Erase Example in C (Unmapped Latches)

```
int writeAddressL, writeAddressH;
int offset;
// Set ERASE, WREN and configure NVMOP for page erase (see data sheet)
NVMCON = 0x40xx;
// Set target write address
offset = (writeAddressL & 0xFF00); // Mask to page boundary
TBLPAG = writeAddressH;
__builtin_tblwt1(offset, 0); // Dummy TBLWT to load address

__builtin_disi(5); // Disable interrupts for NVM unlock
__builtin_write_NVM(); // Start write cycle
```

Example 4-2: Page Erase Example in C (Mapped Latches)

```
int writeAddressL, writeAddressH;
int offset;
// Set ERASE, WREN and configure NVMOP for page erase (see data sheet)
NVMCON = 0x40xx;
// Set target write address
NVMADR = (writeAddressL & 0xFF00); // Page address to erase
NVMADRH = writeAddressH;

__builtin_disi(5); // Disable interrupts for NVM unlock
__builtin_write_NVM(); // Start write cycle
```

4.2.3.1 Row Erase

Some PIC24F devices support individual row erases, making it unnecessary to erase the entire Flash page. The process is similar to the page erase procedure. Refer to the “**Flash Program Memory**” chapter of the device data sheet or the device programming specification for availability.

4.2.4 PROGRAM THE PAGE

After the program memory page has been erased, it can be written to from data RAM with the updated image. Most commonly, this either involves writing one or two instruction words, or an entire row.

As with table operations, there are different algorithms for devices with unmapped and memory-mapped write latches.

4.2.4.1 Single-Word Programming

Single-word programming ([Example 4-3](#)) programs a single 24-bit Flash memory location. It is available only in devices with unmapped write latches. The destination address should be masked with FFFFEh to ensure an even address.

To perform:

1. Set the NVMOPx bits field for a word program operation (refer to the device data sheet for the proper value).
2. Write the destination address to the TBLPAG and a W register.
3. Load write latches with the RAM image write data (see [Section 3.8 “Using Table Write Instructions”](#)).
4. Disable interrupts.
5. Write the key sequence to the NVMKEY register (see [Section 4.1.2 “NVMKEY Register”](#)).
6. Set the WR bit (NVMCOM<15>). This will start the program cycle. The WR bit is cleared when the erase cycle is complete.

Example 4-3: Single-Word Programming in C

```
int  writeAddressL, writeAddressH;
int  writeDataL = 0xXXXX;
int  writeDataH = 0x00XX;
int  offset;
// Set WREN and NVMOP for double word program mode (see data sheet)
NVMCON = 0x40xx;

// Set target write address
offset = (writeAddressL & 0xFFFE); // Mask to even address
TBLPAG = writeAddressH;
__builtin_tblwtl(offset, writeDataL); // Load write latches
__builtin_tblwth(offset, writeDataH);

__builtin_disi(5); // Disable interrupts for NVM unlock
__builtin_write_NVM(); // Start write cycle
```

4.2.4.2 Double-Word Programming

Double-word programming ([Example 4-4](#)) programs two 24-bit Flash memory locations. It is only available on devices with memory-mapped write latches.

To perform:

1. Set the NVMOPx bits field for a double-word program operation (refer to the device data sheet for the proper value).
2. Write the start address of the write latches to the TBLPAG and Wn registers.
3. Write the destination address to the NVMADR/NVMADRU registers.
4. Load write latches with the RAM image write data (see [Section 3.8 “Using Table Write Instructions”](#)).
5. Disable interrupts.
6. Write the key sequence to the NVMKEY register (see [Section 4.1.2 “NVMKEY Register”](#)).
7. Set the WR bit (NVMCOM<15>). This will start the program cycle. The WR bit is cleared when the erase cycle is complete.

Example 4-4: Double-Word Programming in C

```
int   writeDataL = 0xFFFF;
int   writeDataH = 0x00XX;
int   writeData2L = 0xFFFF;
int   writeData2H = 0x00XX;
int   addrOffset;
int   WriteAddressL, WriteAddressH;

NVMCON = 0x40xx;           // Set WREN and word program mode
TBLPAG = 0xFA;             // Write latch upper address
NVMADRL = WriteAddressL;   // Set target write address
NVMADRH = WriteAddressH;

__builtin_tblwtl(0,writeDataL); // Load write latches
__builtin_tblwth(0,writeDataH);
__builtin_tblwtl(0x2,writeData2L);
__builtin_tblwth(0x2,writeData2H);
__builtin_disi(5);         // Disable interrupts for NVM unlock
__builtin_write_NVM();     // Initiate write
```

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4.2.4.3 Row Programming (Unmapped Write Latches)

Note: Not all devices support row programming. Refer to the specific device data sheet for availability.

Row programming is similar to word programming and utilizes a larger number of write latches to program a whole row at a time. Eight (8) row programming operations are needed to program one page. The target address must be on a row boundary start address.

Row programming may be implemented on devices with either unmapped or memory-mapped write latches. [Example 4-5](#) shows the method for devices with unmapped latches.

To program a row of Flash memory:

1. Set the NVMOPx bits field for a word program operation (refer to the device data sheet for the proper value).
2. Write the start address of the row to be programmed into the TBLPAG and W registers.
3. Load write latches with the RAM image write data (see [Section 3.8 “Using Table Write Instructions”](#)).
4. Disable interrupts.
5. Write the key sequence to the NVMKEY register (see [Section 4.1.2 “NVMKEY Register”](#)).
6. Set the WR bit (NVMCON<15>) to start the program cycle. The WR bit is cleared when the erase cycle is complete.

Example 4-5: Row Programming in C with Built-in Functions (Unmapped Latches)

```
int   writeDataL[64];           // Lower word write data
char  writeDataH[64];           // Upper byte write data
int   i, offset, writeAddressL, writeAddressH;
// Set WREN and NVMOP bits for row programming (see data sheet)
NVMCON = 0x40xx;

// Set target write address
offset = (writeAddressL & 0xFF80); // Mask to start of row
TBLPAG = writeAddressH;

for(i=0; i<=63; i++)           // Load 64 write latches with data
{
    // Increment program address by 2
    __builtin_tblwtl((offset + (i * 2)), writeDataL[i]);
    __builtin_tblwth((offset + (i * 2)), writeDataH[i]);
}
__builtin_disi(5);             // Disable interrupts for NVM unlock
__builtin_write_NVM();         // Start write cycle
```

4.2.4.4 Row Programming (Memory-Mapped Write Latches)

The process for row programming in devices with memory-mapped latches is similar to that for devices with unmapped latches. [Example 4-6](#) shows the procedure.

To program a row of Flash memory:

1. Set the NVMOPx bits field for a word program operation (the value is device-specific; refer to the data sheet for the proper value).
2. Write the start address of the write latches to the TBLPAG and Wn registers.
3. Write the start address of the row to be programmed into the NVMADR and NVMADRU registers.
4. Load write latches with the RAM image write data (see [Section 3.8 “Using Table Write Instructions”](#)).
5. Disable interrupts.
6. Write the key sequence to the NVMKEY register (see [Section 4.1.2 “NVMKEY Register”](#)).
7. Set the WR bit (NVMCON<15>) to start the program cycle. The WR bit is cleared when the erase cycle is complete.

Example 4-6: Row Programming in C with Built-in Functions (Memory-Mapped)

```
int  varWordL[64];
int  varWordH[64];
int  WriteAddressL, WriteAddressH;
int  i;
NVMCON = 0x40xx;           // Set WREN and row program mode
TBLPAG = 0xFA;
NVMADRL = WriteAddressH;   // set target write address
NVMADRH = WriteAddressL;
for(i=0; i<=63; i++)      // load write latches with data
{                          // to be written
  __builtin_tblwtl((i * 2), varWordL[i]);
  __builtin_tblwth((i * 2), varWordH[i]);
}
__builtin_disi(5);         // Disable interrupts
__builtin_write_NVM();     // Start write cycle
```

5.0 PROGRAM SPACE VISIBILITY AND EXTENDED DATA SPACE (PSV AND EDS)

For all PIC24F devices, table instructions (see [Section 3.0 “Table Operation Instructions”](#)) can be used to access data within the program memory space. This is useful when data only needs to be read or written, one byte or word at a time.

It is also possible to map 16K word pages of the program memory space into the upper 32 Kbytes of the data address space. This allows an effective expansion of the data space beyond its normal 64-Kbyte addressing limits, as well as transparent access without the use of table instructions.

All PIC24F devices are able to map any page in the implemented program memory space into the data space for read-only access. This feature is known as Program Space Visibility (PSV). Additionally, some devices expand PSV with read/write access to an extended range of virtual memory pages. This feature is particularly useful for peripherals, such as the Advanced Graphics Controller, which has high data throughput requirements. This expansion of PSV is known as Extended Data Space (EDS).

PSV and EDS are implemented as features of the data memory. For a detailed description, refer to the *“dsPIC33/PIC24 Family Reference Manual”*, **“PIC24F Data Memory”** (DS30009717) or **“Data Memory with Extended Data Space (EDS)”** (DS39733).

5.1 PSV and Instruction Stalls

For more information about instruction Stalls using PSV, refer to **“CPU”** (DS39703) in the *“dsPIC33/PIC24 Family Reference Manual”*.

6.0 ERROR CORRECTING CODE (ECC)

In order to improve program memory performance and durability, select PIC24F devices include Error Correcting Code (ECC) functionality as an integral part of the Flash memory controller. ECC can determine the presence of single bit errors in program data, including which bit is in error, and correct the data without user intervention. When implemented, ECC is automatic and cannot be disabled.

When data is written to program memory, the controller generates and stores a 7-bit ECC for every pair of (24-bit) instruction words. ECC data is not memory-mapped and is inaccessible to the user. When the data is read back, the controller calculates parity on it and compares it to the previously stored ECC value. If a mismatch occurs, there are two possible outcomes:

- Single bit errors are automatically identified and corrected on read back.
- Double-bit errors will generate an ECC double-bit error trap.

7.0 LOW-POWER OPERATION

Most PIC24F devices include a feature that allows program memory to be powered down when the device enters Sleep mode, thereby providing incremental reduction to Power-Down Current (IPD). The feature is controlled by the PMSLP bit (RCON<8>); it is also designated in some devices as the VREGS bit, but with the same functionality.

When PMSLP is clear, bias voltage is removed from program memory, while the device's on-chip voltage regulator enters Standby mode. When the bit is set, program memory remains under bias while the device is in Sleep mode. While leaving PMSLP clear reduces power-down current, it also increases the wake-up delay from Sleep.

8.0 REGISTER MAP

A summary of the Special Function Registers (SFRs) associated with the PIC24F Flash Program Memory is provided in [Table 8-1](#).

Table 8-1: Special Function Registers Associated with Flash Program Memory⁽¹⁾

File Name	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets ⁽²⁾
TBLPAG	—	—	—	—	—	—	—	—	Table Page Address Pointer								0000
NVMCON	WR	WREN	WRERR	NVMPIDL	PGMONLY ⁽³⁾	—	—	—	—	ERASE	NVMOP5 ⁽³⁾	NVMOP4 ⁽³⁾	NVMOP3	NVMOP2	NVMOP1	NVMOP0	0000
NVMKEY	—	—	—	—	—	—	—	—	NVMKEY<7:0>								0000
NVMADR	Flash Program Memory Destination Address Register, Lower Word																0000
NVMADRU	—	—	—	—	—	—	—	—	Flash Program Memory Destination Address Register, Upper Byte								--00

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: Please refer to the device data sheet for specific memory map details.

2: Reset value shown is for POR only. Value on other Reset states is dependent on the state of memory write or erase operations at the time of Reset.

3: Not implemented on all devices; refer to the specific device data sheet for more information.

9.0 RELATED APPLICATION NOTES

This section lists application notes that are related to this section of the manual. These application notes may not be written specifically for the dsPIC33 or PIC24 product families, but the concepts are pertinent and could be used with modification and possible limitations.

The current application notes related to the PIC24F Flash Program Memory are:

Title	Application Note #
No related application notes at this time.	

Note: Please visit the Microchip web site (www.microchip.com) for additional Application Notes and code examples for the dsPIC33 and PIC24 families of devices.

10.0 REVISION HISTORY

Revision A (January 2007)

This is the initial released revision of this document.

Revision B (July 2010)

This revision includes the following updates:

- Updated the following sections to include information on devices with only one holding latch:
 - **Section 4.6.2.1 “Table Write Holding Latches”**
 - **Section 4.6.2.2 “Writing a Single Program Memory Latch in Word/Byte Mode”**
- Updated **Section 4.6.3.1 “RTSP Operation”** to include information on devices with multiple holding latches
- Notes:
 - Added a note with information to customers for utilizing family reference manual sections and data sheets as a joint reference (see note above **Section 4.1 “Program Memory Address Map”**).
 - Added a shaded note on availability of PSV in devices with EDS after the first paragraph in **Section 4.4 “Program Space Visibility (PSV) from Data Space”**.
 - Added Note 4 to the Nonvolatile Flash Memory Control Register (see Register 4-1).
 - Added Note 3 to the shaded note in **Section 4.7.1 “Flash Row Program Memory Programming Algorithm”**.
- Minor edits to text and formatting have been incorporated throughout the document

Revision C (April 2015)

Complete revision of the document to parallel the updated structure of the Dual Partition program memory description presented in **“Dual Partition Flash Program Memory”** (DS70005156). Contents are also updated to include information on PIC24F K-Flash devices.

Updates the title to “PIC24F Flash Program Memory” for clarity.

Updates the document format and removes the previously assigned master section number as part of the realignment of PIC24 technical documentation. The document reference number format is also updated.

Major systemic changes to content include:

- The default program memory map in previous revisions has been redesigned ([Figure 2-1](#)) to more closely reflect the presentation shown in device data sheets.
- [Section 2.1 “Vector Area”](#) has been greatly expanded, and [Figure 2-2](#) added, to cover the two versions of IVT mapping that now exist in PIC24F devices (subsequent figures are renumbered accordingly).
- The discussion of Flash Configuration Words for J-Flash devices has been added.
- Discussion of write latches for Table Write operations is moved to [Section 3.4 “Table Writes and Write Latches”](#), and expanded to differentiate between the use of memory-mapped and unmapped write latches.
- [Section 3.8 “Using Table Write Instructions”](#) and [Section 4.2 “Run-Time Self-Programming \(RTSP\)”](#) have been extensively updated to include references to double-word programming, and to differentiate between devices with memory-mapped and unmapped write latches. [Example 3-7](#), [Example 3-8](#), [Example 4-5](#) and [Example 4-6](#) are added as part of this update.
- The discussion of Program Space Visibility (PSV) in previous versions has been moved in its entirety to **“PIC24F Data Memory”** (DS30009717).
- All existing code examples have been updated to reflect changes in Microchip’s development tools.
- The discussion of operation in Low-Power modes has been added.

Minor typographic corrections and updates are also incorporated throughout the document.

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Revision D (September 2017)

Updates page erase instructions in [Section 4.2.3 “Erase the Page”](#).

Updates [Example 4-1](#), [Example 4-6](#) and adds new [Example 4-2](#).

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NOTES:

Note the following details of the code protection feature on Microchip devices:

- Microchip products meet the specification contained in their particular Microchip Data Sheet.
- Microchip believes that its family of products is one of the most secure families of its kind on the market today, when used in the intended manner and under normal conditions.
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ISBN: 978-1-5224-2167-2



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